|  |  |   |                          |               | G/          | NPAT U         | NIVERSITY                  | ,                |                  |           |  |  |
|--|--|---|--------------------------|---------------|-------------|----------------|----------------------------|------------------|------------------|-----------|--|--|
|  |  |   |                          | ΕΔΟΙΙΙΤ       | Y OF F      | NGINEE         | RING & TE                  | CHNOLOGY         | /                |           |  |  |
| Drogra   | mme  |   |                          |               |             | INOINLL        | Branch/Spec.               |                  |                  |           |  |  |
| Programme<br>Semester  |  |   | Bachelor of Technology V |               |             | Version        | Marine Engineering 2.1.1.1 |                  |                  |           |  |  |
| Effective from Academ  |  |   | <u> </u>                 |               | 201         | L7-18          |                            |                  |                  | luly 2015 |  |  |
|  | t code   |   |                          |               |             | , 2010         |                            |                  |                  |           |  |  |
|  |  | Teaching scheme Examination scheme (Marks)  |                          |               |             |                |                            |                  |                  |           |  |  |
| (Per week) Lectur  |  |   |                          | (Lab.)        | o.) Total   |                | CE                         | CEE              | EE Total         |           |  |  |
| (Per v   | weekj  | L   | TU                       | Р             | TW          | TOLAI          |                            | CE               | SEE              | TOLAT     |  |  |
| Credit   |  | 3   | 0                        | 1             | 0           | 4              | Theory                     | 40               | 60               | 100       |  |  |
| Hours  |  | 3   | 0                        | 2             | 0           | 5              | Practical                  | 25               | 25               | 50        |  |  |
| Pre-requisites:  |  |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  |  |   |                          |               |             |                |                            |                  |                  |           |  |  |
| Learning Outcome:  |  |   |                          |               |             |                |                            |                  |                  |           |  |  |
| After successful completion of the course, student will understand about   |  |   |                          |               |             |                |                            |                  |                  |           |  |  |
| <ul> <li>Comply with the TAR (Training Assessment Record – Appendix I) Book Competency number 9.8 &amp; 9.9</li> </ul> |  |   |                          |               |             |                |                            |                  |                  |           |  |  |
| Theory syllabus  |  |   |                          |               |             |                |                            |                  |                  |           |  |  |
| Unit   |  | _   |                          |               |             | Conter         | nt                         |                  |                  | Hrs 7     |  |  |
| 1  | Free vibrations:   |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  | •  |   |                          | Vibration     | s, Linear   | motion of      | an elastic syste           | m, Angular mo    | tion of an elas  | tic       |  |  |
|  |  | system  |                          |               |             |                |                            |                  |                  |           |  |  |
|  | <ul> <li>Differential equation of motion. Free Vibration of springs in series and parallel. Simple and<br/>Compound pendulums, Single and two degrees of freedom.</li> </ul>   |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  |  | Compo   | ouna pen                 | iauiums, S    | ingie and   | i two degree   | es of freedom.             |                  |                  |           |  |  |
| 2  | Damno  | d vibra   | tions                    |               |             |                |                            |                  |                  | 6         |  |  |
| 2  | ·  |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  | <ul> <li>Idea of Viscous and Coulomb damping, Linear and angular vibrations with viscous damping,</li> <li>Forced damped liner and angular Vibrations, Periodic movement of support.</li> </ul>  |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  |  | 101000  | dampee                   | inici ana     | angalai     | vibrations, i  | criodic movem              | ent or support.  |                  |           |  |  |
| 3  | Forced vibrations:   |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  | Forced Linear and angular vibrations, periodic force transmitted to support, periodic movement   |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  | of the support.  Periodic Motion: simple Harmonic motion; Application of S, H, M. to masses and springs. Simple  |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  |  |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  |  | Pendu   | lum and                  | Compound      | d Pendulı   | ım. Centrifu   | gal Force and its          | application to o | conical pendului | m.        |  |  |
|  | Unloaded Governor, Curved tracks and machine parts, stress in thin rim due to centrifugal  |   |                          |               |             |                |                            |                  |                  | gal       |  |  |
|  |  | action.   |                          |               |             |                |                            |                  |                  |           |  |  |
| 4  | Forced   | -   | d Vibrat                 |               |             |                |                            |                  |                  | 4         |  |  |
|  | •  |   |                          | ential equa   | ition of m  | notion and f   | ind amplitude, f           | requency         |                  |           |  |  |
| 5  | <ul> <li>Torsional vibrations:</li> <li>Single rotor system, rotor at end and rotor in the middle. Effect of inertia of Shaft, Two rotor system, rotors at both ends and rotors at one end. Three rotor and multirotor systems. Torsionally equivalent shafts, Geared system.</li> </ul> |   |                          |               |             |                |                            |                  | 7                |           |  |  |
|  |  |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  |  |   |                          |               |             |                |                            |                  | is.              |           |  |  |
| 6  | Transit  |   |                          | of beams:     | arts, Gear  | rea system.    |                            |                  |                  | 10        |  |  |
| O  |  |   |                          |               | offeet a    | f tha mass a   | ftha haam Ena              | ray mothed say   | oral concentrati |           |  |  |
|  | Single Concentrated load, effect of the mass of the beam, Energy method several concentrated loads uniformly distributed load. Dunkerloy's empirical method for several concentrated loads.  |   |                          |               |             |                |                            |                  |                  |           |  |  |
|  | •  | <ul> <li>Loads uniformly distributed load, Dunkerley's empirical method for several concentrated loads.</li> <li>Whirling of shafts Whirling of shafts, critical speed, effect of slope of the disc, effect of end</li> </ul> |                          |               |             |                |                            |                  |                  |           |  |  |
|  |  | thrusts   | _                        | aito VVIIIIII | ing UI Sile | arto, Critical | speed, effect 0            | i siope of the 0 | nse, enect of el | iu        |  |  |
| 7  | Balanci  |   | ·. /                     |               |             |                |                            |                  |                  | 9         |  |  |
| •  | - Daranci  | p.  |                          |               |             |                |                            |                  |                  |           |  |  |

|   | Balancing of masses rotating in different planes, dynamic forces at bearings, Primary and secondary balance of multi cylinder inline Engines and Configurations.   |    |  |  |  |  |  |  |  |
|---|--|----|--|--|--|--|--|--|--|
| 8 | <ul> <li>Gyroscope:         <ul> <li>Gyroscopic couple, Vector representation of torque and angular momentum, steady rectangular precession, vector treatment; Steady conical precession;</li> <li>Motion involving steady precession; Application to Ship's stabilization.</li> </ul> </li> </ul> | 5  |  |  |  |  |  |  |  |
|   | TOTAL  | 54 |  |  |  |  |  |  |  |

## Practical content

- To study the undammed free vibrations of equivalent spring mass system;
- To determine the radius of gyration of a given bar by using bifilar suspension;
- To study gyroscopic effect and to find out gyroscopic couple both in magnitude and direction;
- To study free vibrations of two rotor system and to determine the natural frequency of vibrations theoretically and experimentally;
- Static and dynamic balancing of shaft;
- To study the damped torsion oscillation and determine the damped coefficient;
- To determine the characteristic curves of sleeve position against controlling force and speed for the governor;

## **Text Books**

1 Dynamics of machinery - Farazdak Haidri

## **Reference Books**

- Advanced Mechanics of Machines J. Hannah & R. C. Stephens
- 2 Theory of Machines P. L. Ballaney